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DOCUMENT HISTORY

Version	Date	Modification
1	04/11/2011	first version
2	02/04/2012	Add chapter on Camera

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LIST OF ACRONYMS

PV Peak to Valley
rms Root Mean Square

APPLICABLE DOCUMENTS

[AD1]

REFERENCE DOCUMENTS

[RD1] ASTRI-IR-OAB-3100-009 *"The optical layout of the ASTRI prototype: 4 meter Schwarzschild-Couder Cherenkov telescope for CTA with 10° of field of view"*

[RD2]

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1. INTRODUCTION

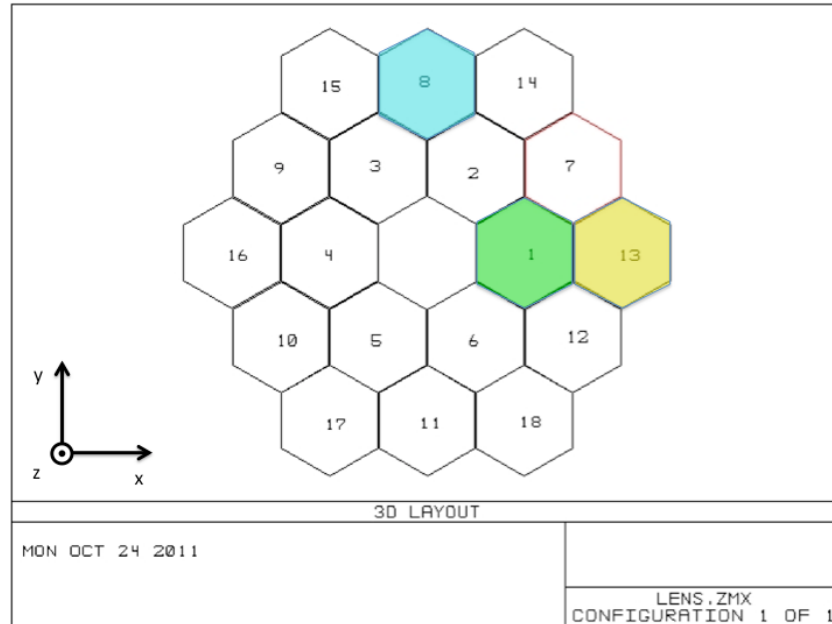
This document describes the Error Budget Tree to be used for the design and verification of the structure and mirrors subsystems of the ASTRI telescope prototype.

This document is a living document. This means that the numbers adopted for each parameter can be subject of changes depending from the outcomes of the structural analyses and/or technological developments.

2. DEFINITIONS

2.1 Reference system

The reference system is defined as in figure 1, if not explicitly stated. The z axis is the optical axis and it points toward the M2.



According to the M1 segments numeration, we give the nominal position of the centers of each hexagon. The numbers are in mm unit.

N° dell'esagono	X	Y	Z
1	856.485	0.0	44.229
2	428.242	741.378	44.229
3	-428.242	741.378	44.229
4	-856.485	0	44.229
5	-428.242	-741.378	44.229
6	428.242	-741.378	44.229
7	1280.522	738.775	129.652
8	0.0	1478.620	129.652
9	-1280.522	739.310	129.652
10	-1280.522	-739.319	129.652
11	0.0	-1478.620	129.652
12	1280.522	-739.310	129.652
13	1704.850	0.0	170.581
14	852.425	1476.443	170.581
15	-852.425	1476.443	170.581
16	-1704.850	0.0	170.581
17	-852.425	-1476.443	170.581
18	852.425	-1476.443	170.581

The segments numbered 1, 8 and 13 are used as reference and they correspond to the color index green, light blue and yellow respectively.

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2.2 Sensitivity

As described in [RD1] the optical layout of the ASTRI prototype has the energy concentration (ensquared energy) greater then 80% into the Cherenkov pixels along the entire field of view.

This definition is meaningful taking into account the entire telescope optical design and is not referred to the single mirror segments, like in the Davies-Cotton case. Considering this fact the Error Budget Tree hereafter described can be compiled in such a way the global effect of all contributions keeps the energy concentration (ensquared energy) better then (or equal to) 70%.

This can be translated in a PV error budget equal to 120 μm and slope error budget equal to 60" rms.

3. ERROR BUDGET TREE RELATED TO M1

Let's consider the secondary mirror M2 being monolithic, infinitely rigid and having the nominal profile.

		Value	Units	Comments
1. M1 segments profile errors				
1.1. Manufacturing				
	a. Mold	30	-- $\mu\text{m PV}$	It comes from FLABEG, no/very poor control on it.
		10	-- " rms	The rms is sampled at least with a grid of 25 mm of pitch.
		50	-- $\mu\text{m PV}$	It comes from FLABEG, limited control on it.
		10	-- " rms	The rms is sampled at least with a grid of 25 mm of pitch.
		--	6 '	Axial (normal to the surface on the hexagon center) rotation of the glass profile wrt the nominal one.
				It is equivalent to 0.87 mm over the length of the hexagonal side.
		TBD	-- $\mu\text{m PV}$	Contribution of the cold shaping step (could be also improvements)
		TBD	-- " rms	
	SUBTOTAL	58	-- $\mu\text{m PV}$	Quadratic propagation
		--	6 '	
1.2. Structural				
	a. Mounting	40	$\mu\text{m PV}$	Contribution of the mounting supports (e.g. gluing of the interfaces, ...)
		2	" rms	The shape will be modified only locally.
	b. Gravity	30	$\mu\text{m PV}$	Contribution of the normal gravity
		TBC	" rms	
	c. Operative wind	30	$\mu\text{m PV}$	Contribution of the operative wind
		TBC	" rms	
	d. Operative temp.	1	$\mu\text{m PV}$	Homogeneous temperature shift up to $\pm 20^\circ\text{C}$
	SUB TOTAL	58	$\mu\text{m PV}$	Quadratic propagation
	GRAND TOTAL	82	$\mu\text{m PV}$	Error budget in quadratic propagation.
2. M1 segments alignment errors				
2.1 Translations				
	a. x	± 2	mm	These values are referred to the positions of the centers of the hexagons as reported in Table 1.
	b. y	± 2	mm	
	c. z	± 4	mm	

	2.2 Rotations				
	a. z'	± 4	'	z' is defined as the axis parallel to the z (optical axis) passing through the center of the hexagons.	
	2.3 Tilts				
	a. x	± 30	"		
	b. y	± 30	"		

Not appreciable degradation (i.e. $<5\%$) of the ensquared energy is reported within these values. There is no need to actively correct with actuators within these ranges. However, these values shall be used to define the accuracy and the range of the actuators.

4. ERROR BUDGET TREE RELATED TO M2

4.1 Profile errors

Let's consider now the M1 segments being perfectly aligned, infinitely rigid (both the mirrors themselves and the telescope structure) and having the nominal profile.

We consider now the contributions coming from a not perfect secondary mirror.

4.2 Alignment errors

The positioning errors along (x, y) and the relative tilts translate almost completely in pointing errors of the telescope (the contribution to the ensquared energy is negligible).

The error along z is a defocusing of the telescope and can be correct adjusting the 3 actuators of M2.

			Value	Units	Comments
3. M2 profile errors					
	3.1. Manufacturing				
		a. Mold	120	$\mu\text{m PV}$	It comes from FLABEG, no/very poor control on it.
			40	" rms	The rms is sampled at least with a grid of 25 mm of pitch.
		b. Replication process	200	$\mu\text{m PV}$	It comes from FLABEG, limited control on it.
			40	" rms	The rms is sampled at least with a grid of 25 mm of pitch.
		c. Glass cutting	n.a.	'	Axial (normal to the surface on the hexagon center) rotation of the glass profile wrt the nominal one.
		d. Integration	TBD TBD	$\mu\text{m PV}$ " rms	Contribution of the cold shaping step (could be also improvements)
		SUBTOTAL	217 (54)	$\mu\text{m PV}$ $\mu\text{m PV}$	Quadratic propagation (calculated taking into account the demagnification factor, equal to 4)
3.2. Structural					
		a. Mounting	40	$\mu\text{m PV}$	Contribution of the mounting supports (e.g. gluing of the interfaces, ...)
			2	" rms	The shape will be modified only locally.
		b. Gravity	120	$\mu\text{m PV}$	Contribution of the normal gravity
			TBC	" rms	
		c. Operative wind	120	$\mu\text{m PV}$	Contribution of the operative wind
			TBC	" rms	
		d. Operative temp.	4	$\mu\text{m PV}$	Homogeneous temperature shift up to $\pm 20^\circ\text{C}$
		SUBTOTAL	174 (44)	$\mu\text{m PV}$	Quadratic propagation (calculated taking into account the



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			$\mu\text{m PV}$	demagnification factor, equal to 4)
	GRAND TOTAL	278	$\mu\text{m PV}$	Error budget in quadratic propagation.
		(69)	$\mu\text{m PV}$	(calculated taking into account the demagnification factor, equal to 4)
4. M2 alignment errors				
4.1 Translations				
	a. x	± 3	mm	This introduces pointing errors to be modeled with T-points. (1 mm = 38" pointing error)
	b. y	± 3	mm	
	c. z	± 4	mm	
		± 1	mm	Relative to DET
4.2 Rotations				
	a. z	n.a.	'	
4.3 Tilts				
	a. x	10	'	The tilts do not constrain the design of the telescope structure up to the indicated value.
	b. y	10	'	
				Obliviously, this introduces pointing errors to be modeled with T-points.

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5. ERROR BUDGET TREE RELATED TO CAM

5.1 Profile errors

Let's consider now the M1 segments and M2 monolithic mirror perfectly aligned, infinitely rigid (both the mirrors themselves and the telescope structure) and having the nominal profile.

We consider now the contributions coming from a not perfect camera mounting.

5.2 Alignment errors

The positioning errors along (x, y) translate almost completely in pointing errors of the telescope (the contribution to the ensquared energy is negligible). Nevertheless, we fix the maximum displacements to ± 5.5 mm along each axis (x, y) .

Tilts errors along (x, y) of the order of 20 arcmin for each axes can be tolerable.

The error along z is a defocusing of the telescope and is correct adjusting the 3 actuators of M2.