

# ESA Strategy for Human Exploration

*(Lunar Lander)*

*Schiaparelli and his Legacy*  
*Torino, 21 October 2010*

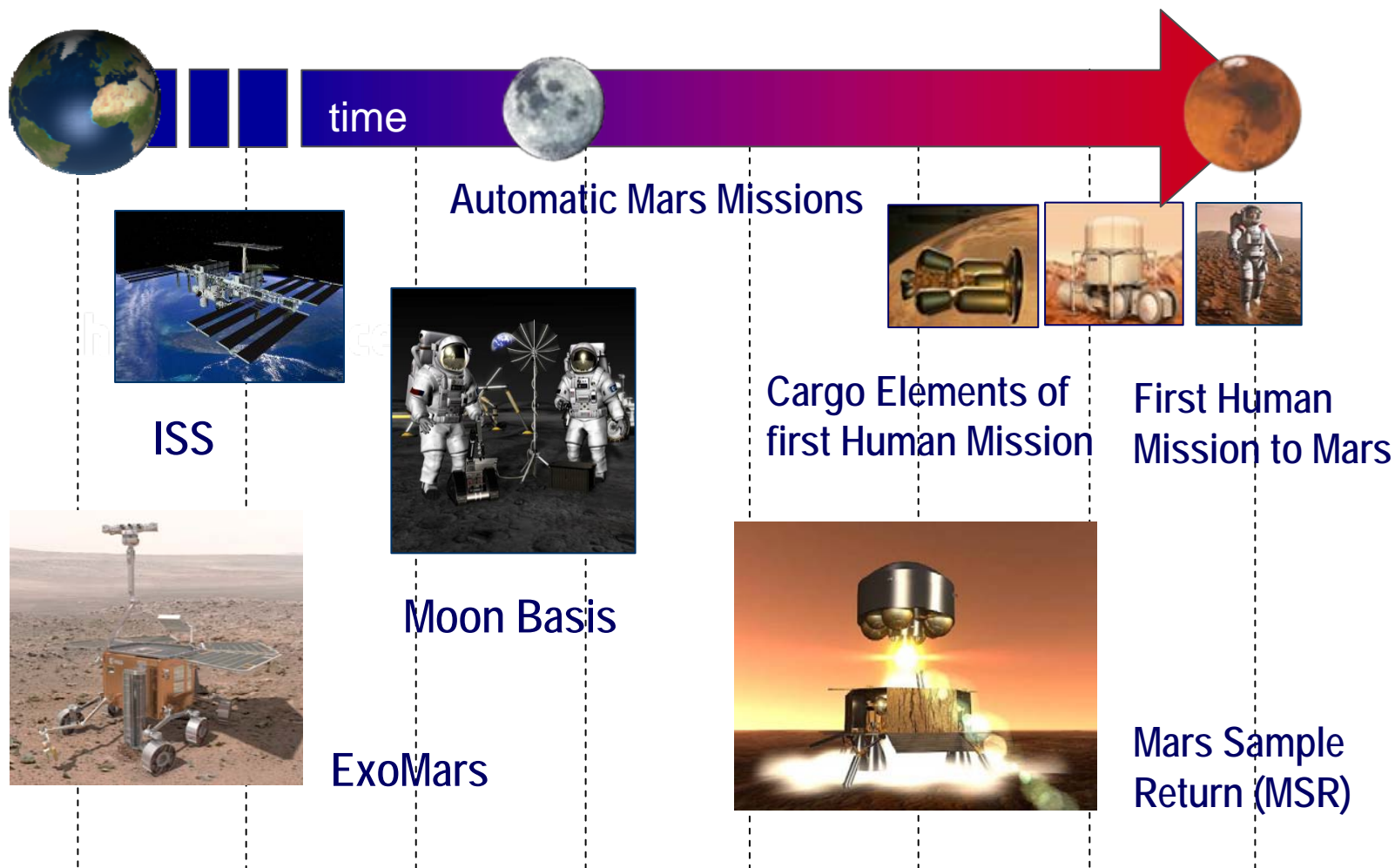
*B. Gardini*  
*D/HSF-E*





# Aurora Programme

## ESA Programme (2001) for the human and robotic exploration of the Solar System

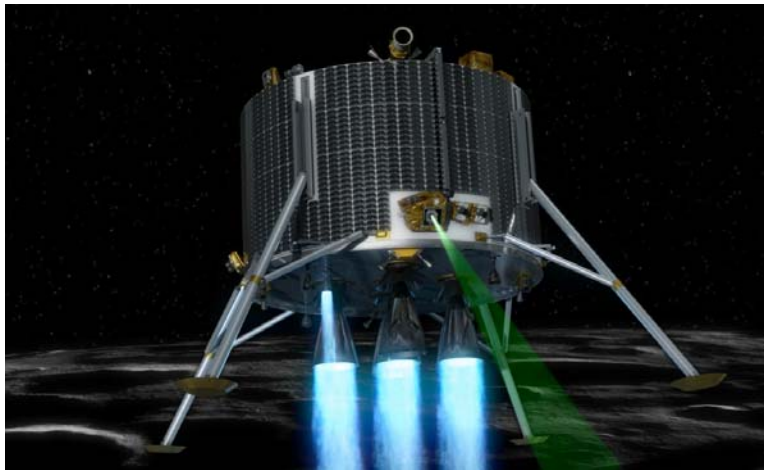


## Lunar Lander Mission Objective **ENABLE SUSTAINABLE EXPLORATION**

primary  
objective

opportunity for  
investigations

### ◆ **Soft Precision Landing with hazard avoidance**



- ◆ **Crew health**
- ◆ **Habitation**
- ◆ **Resources**
- ◆ **Preparations for  
human activities**

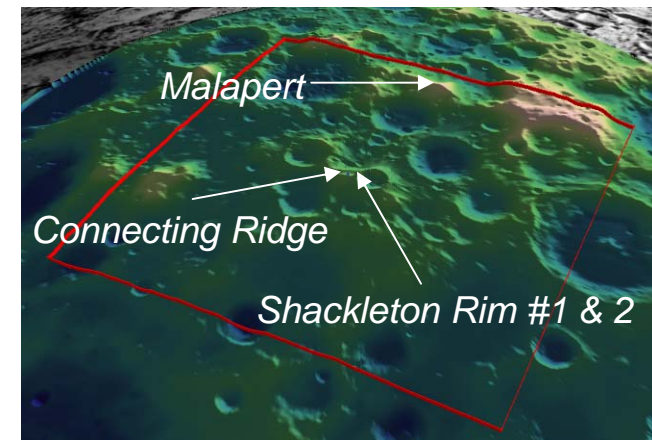


# Landing Site: South Pole

- Polar regions may experience extended periods of illumination (>14days)
- Critically dependent on the local topography in the polar regions: terrain requires very precise navigation and hazard avoidance
- JAXA's Kaguya orbiter surface mapping:
  - ~200m resolution in South Pole region
- 3 parallel analyses performed:
  - Illumination pattern: duration of light/dark
  - Earth communications availability
  - Physical extent of illuminated areas
- Several interesting locations found, but no 'peak of eternal light'



*Courtesy of JAXA*



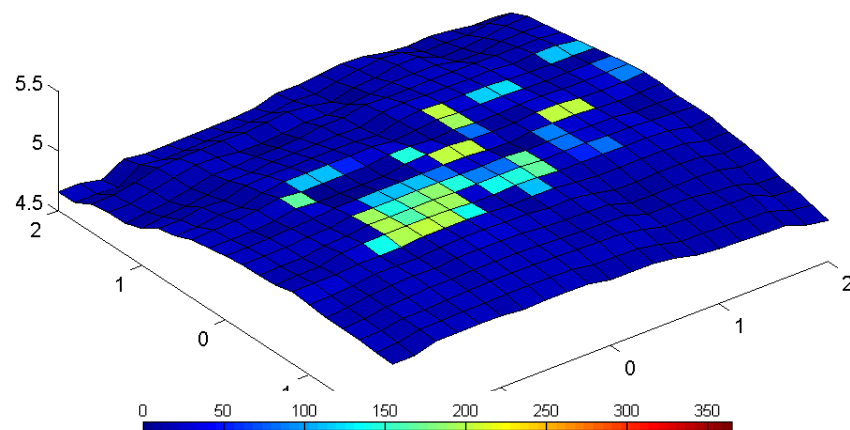
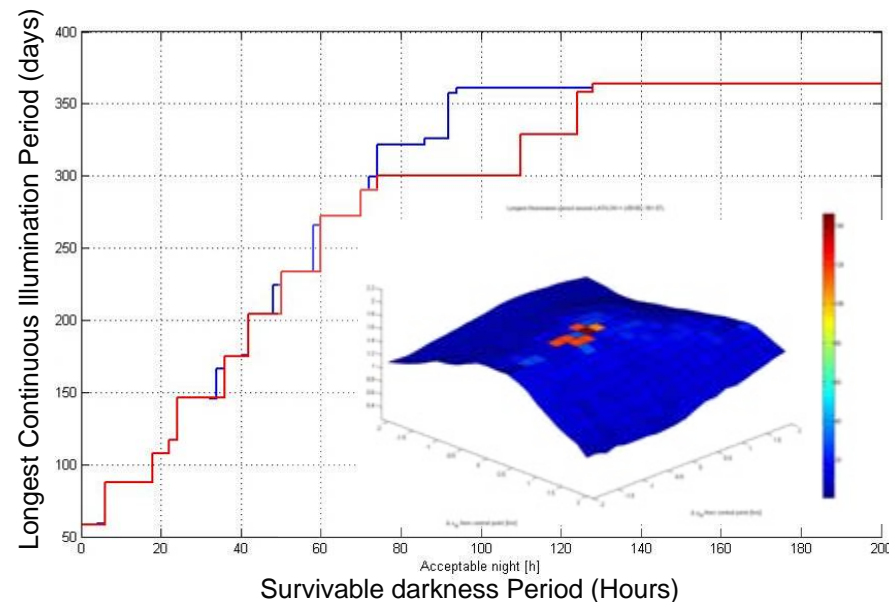
*Courtesy of NASA*



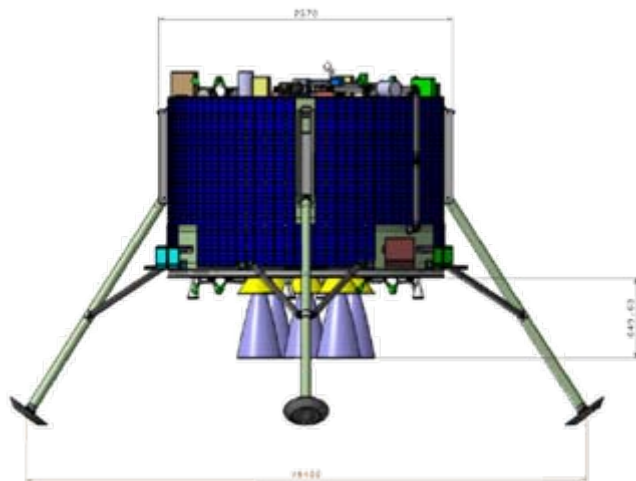


# Topographic Analysis

- Various illumination patterns across the identified sites, strongly date dependent
- Enabling survival of short darkness periods:
  - Can significantly increase the effective illumination duration
  - Can lead to an enlargement of the effective landing areas
- Sites do exist which are illuminated for several months\*; further analysis of new data will help confirm their size
- Analyses shall be repeated in Phase B1 using more accurate data coming in from NASA's Lunar Reconnaissance Orbiter (LRO)
  - \*given the capability to survive for short periods of darkness (up to 10's hours)



Example illumination map, Malapert, filtering out short nights of <55hrs



Phase B1 Contract with Astrium ST  
(Bremen) initiated end July 2010:

- Single stage
- Propulsion: cluster of European engines (500N EAM & 220N ATV)
- Direct Communication To Earth
- Payload capability: ~60 kg total (**tbc in Phase B1**), including all instruments and the associated servicing equipment



Parallel Activities during Phase B1:

- Launcher performance analysis with Arianespace
- Payload definition studies (GSP funded)
- Consultancies about surface hazards analysis (G. Neukum, I. Crawford)

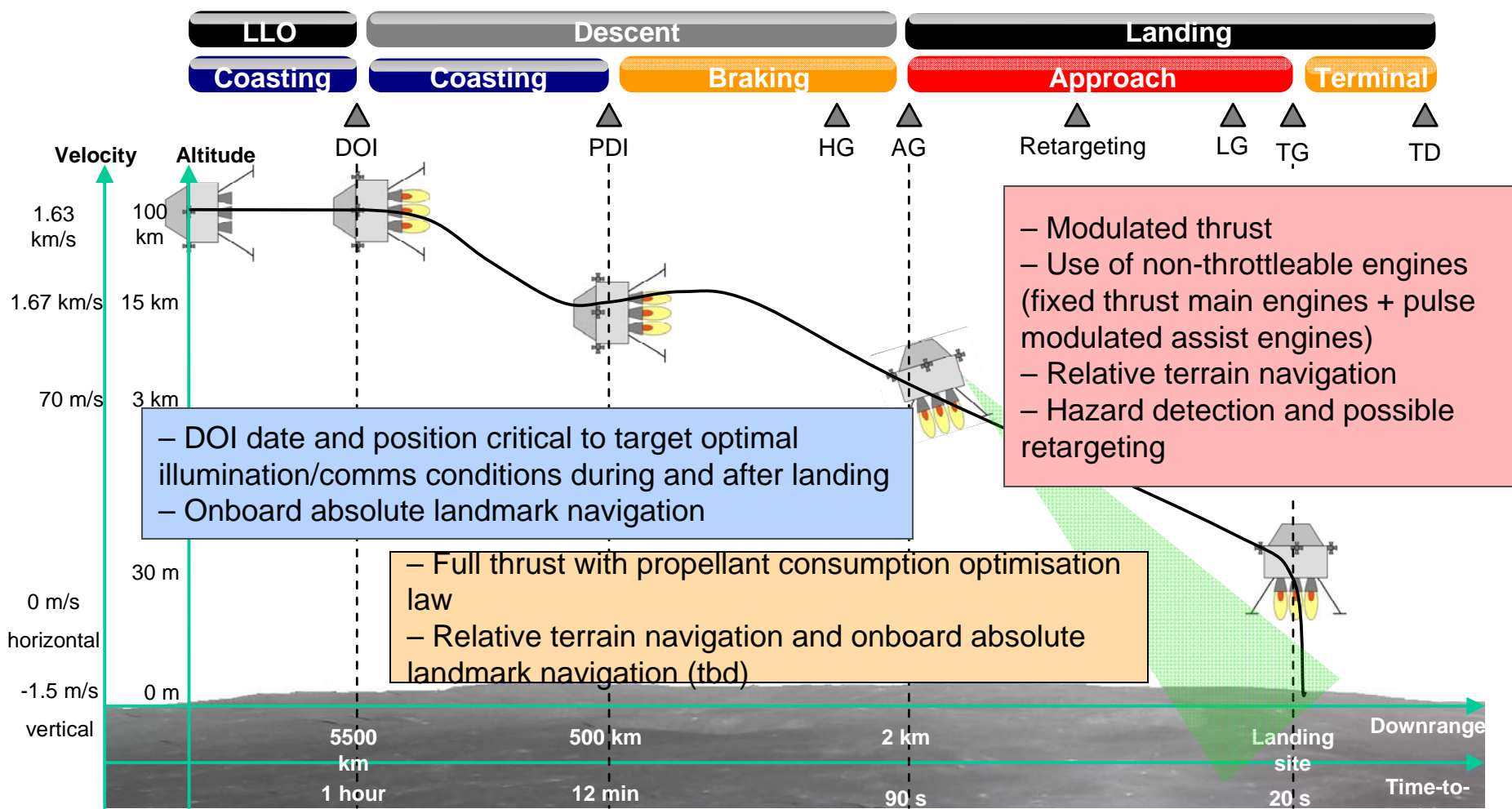
- Launcher: Soyuz 2-1b, with Fregat upper stage
- Launch site: CSG
- Launch period: every 2 weeks
- Launch window: 2 consecutive days
- Launch date: no later than 2018

- ➔ main mission constraint from launcher: **MASS**
- ➔ launch date compatible with favourable illumination/ comms period at the landing site

- Transfer via GTO or HEO:
  - Optimal solution under investigation in Phase B1
- Injection in LTO followed by insertion in LLO (typically 100 km altitude) performed by the spacecraft itself



# Descent & Landing Profile



Note: the velocity, altitude, downrange, delta-V and time values are provided to give an order of magnitude

– Control of touchdown conditions, compatible with landing legs design  
– Engines cut-off

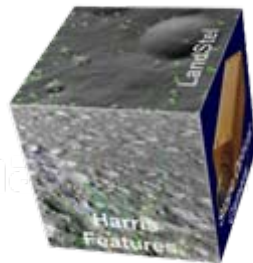


# Soft and Precision Landing Technology

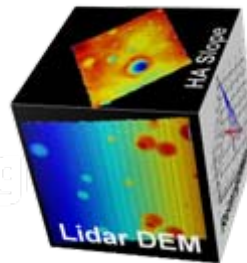
Technology activities developed since 2005 under ESA Aurora Core / TRP programmes and nationally funded R&D activities, are key building blocks in the mission development logic



TRN Sensors:  
Optical camera  
and Lidar



Optical Terrain  
Relative/Absolute<sup>+</sup>  
Navigation  
<sup>+</sup>: ANTARES



Reusable  
GNC and HDA  
Software



COTS Model-based  
Development &  
Validation Framework



Generic  
Avionics  
Platform



Terrestrial  
Dynamics Test  
Facilities

Industries across Europe are already developing the next generation of technologies needed to successfully land on the Lunar surface

# Phase B1 Bread boarding Propulsion

- **Flow interaction test with water:** investigation of interactions and disturbances in the feed system
- **220N thruster hot firing test:** performance characterisation at 2.5 Hz command frequency (1 Hz qualified for ATV)
- **Pressure regulator test:** measurement of regulation accuracy at high mass flows

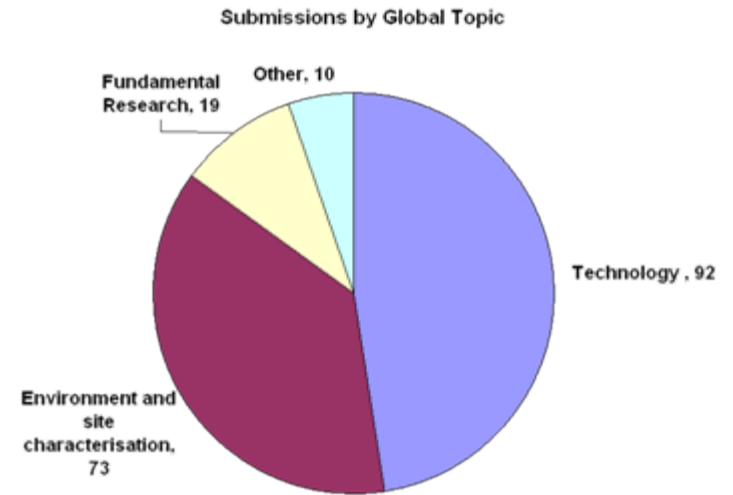


# Phase B1 Bread boarding Navigation & HDA

- **Relative navigation and HDA demonstration test:** test with hardware-in-the-loop on the TRON dynamic test bench (DLR Bremen), with a representative Lunar surface model
- **Absolute navigation rapid prototype:** specification and implementation for systematic performance analyses
- **Absolute navigation demonstration test:** evaluation using the TRON indoor test facility



- Stepwise and transparent process put in place since 2009
- Request for information in March 2009:
  - 194 submissions received, demonstrating widespread interest across Europe and within both industry and academia



- Lunar Exploration Definition Team (external): defines objectives for a precursor mission to lunar exploration by humans
  - Supported by ESA technical experts and Topical Teams
  - Advised by Life Sciences and Physical Sciences Working Groups





# Model Payload

## Model payload (not selected payload)

- Total payload ~60 kg, including payload servicing s/s
- Derived from RFI responses and extensive definition process
- Consistent with mission constraints
- Input to mission system design
- Input to P/L development activities

Heritage	
Flight heritage	
In development for other missions	
Has been subject to studies	
Conceptual	

Priority	
High	
Medium	

	Health	Habitation	Resources	Human Activities	Public Outreach	Mobility
Stereo panoramic imager						
Arm camera						
Experiment in human radiation biology						
Radiation Monitor						
Dust charge and trajectory sensor						
Langmuir probes and booms						
Radio antenna						
Optical microscope						
Atomic force microscope						
Raman (LIBS?)						
Dust chemical reactivity experiment						
Volatiles analysis package						
X-ray spectrometer / Raman optical head						
Mobile Payload Experiment (MPE)						



# Payload Definition Studies

- Objectives:

- Improve instrument definition, interfaces and requirements (Phase 0/A)
- Establish preliminary instrument package design
- Identify opportunities for design and science optimisation: synergy, coordinated operations, commonality
- Establish overall package development plan

Heritage	
Flight heritage	
In development for other missions	
Has been subject to studies	
Conceptual	

- 4 x Payload Definition Activities under GSP

- ITTs in preparation, release expected end October 2010

- Exchange of results between P/L studies and Phase B1 through Project

Payload Studies	
Planned ESA activities	abc
Activities planned outside of ESA	abc

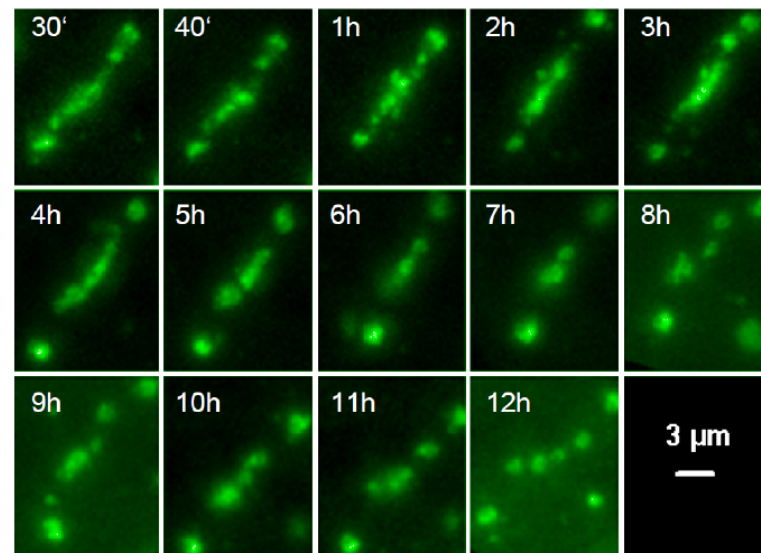
Cameras	Stereo panoramic imager
	Arm camera
Radiation and Effects Package	Experiment in human radiation biology
	Radiation Monitor
Dust Plasma Waves and Fields Package	Dust charge and trajectory sensor
	Langmuir probes and booms
	Radio antenna
Dust Chemistry and Microscopy Package	Optical microscope
	Atomic force microscope
	Raman (LIBS?)
Dust Toxicity	Dust chemical reactivity experiment
Volatiles	Volatiles analysis package
Optional Payloads	X-ray spectrometer / Raman optical head
Contribution In Kind	MPE



# 1. Radiation package

## Automated Microscope for the Examination of Radiation Effects

- Experiment concept from TT-IBER
- Radiation effects on human physiology
- DNA repair mechanisms
  - in human cells
  - following damage by HZE-GCR particles
  - in the Lunar environment
- Techniques applied in terrestrial studies
- Feasibility of lunar payload needs determining
- Potential application to other platforms for exploration preparation



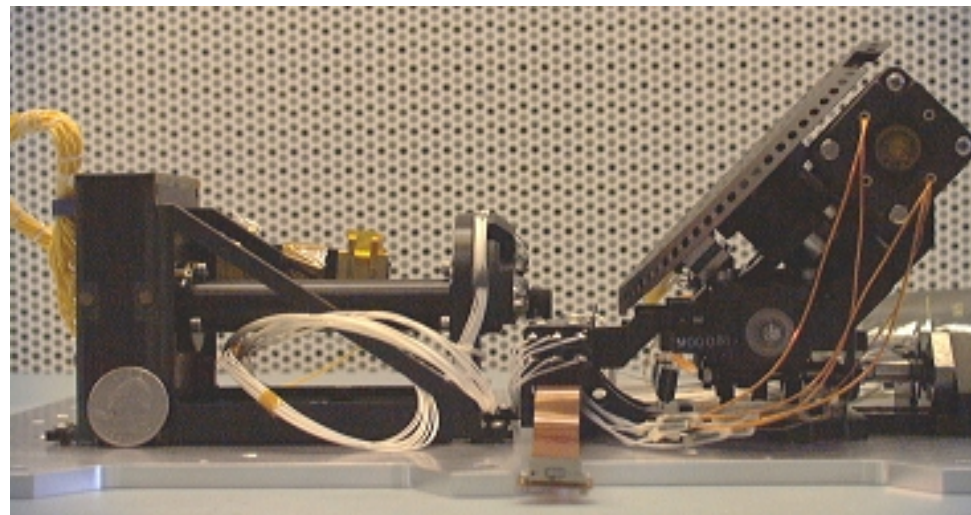
*From Jakob et al., Proc. Natl. Acad. Sci. USA, 2009*



## 2. Lunar Dust Analysis Package

### Lunar Dust Analysis Package

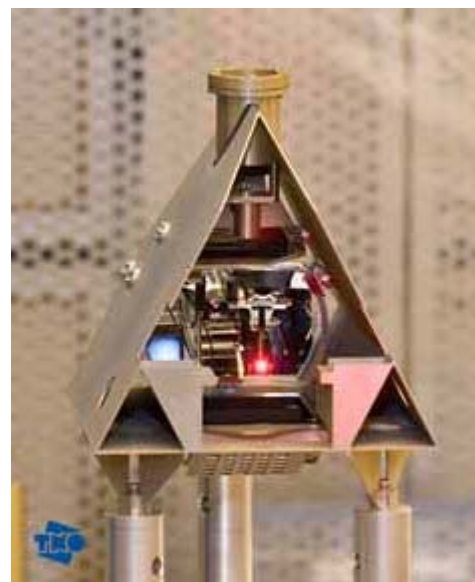
- Size distribution of dust ~10nm - 100 $\mu$ m
- Structure and morphology of grains
- Dust chemistry/mineralogy
- Dust elemental composition?
- OH group, H<sub>2</sub>O



*Phoenix MCA optical and Atomic force microscopes and sample stage.*

### Potential Instruments for consideration

- Optical and Atomic Force Microscopes
  - E.g. Phoenix (MECA) / Beagle 2)
- Raman (+ LIBS?)
  - E.g. Heritage from Exomars



*Raman-LIBS elegant breadboard spectrometer*

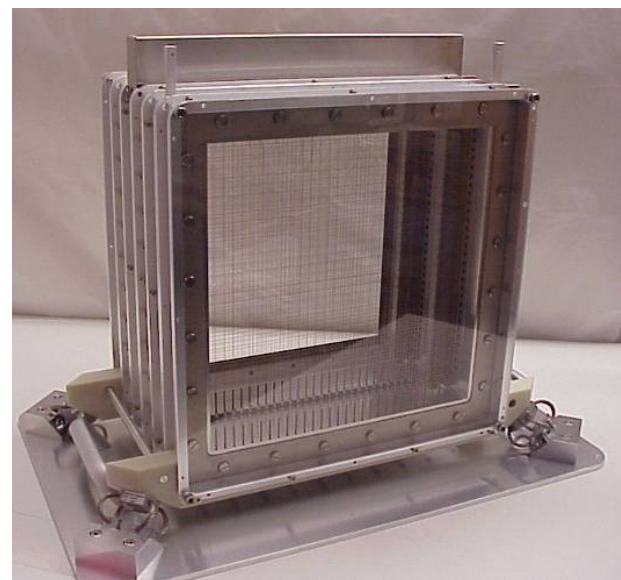




### 3. Lunar Dust Environment and Plasma Package

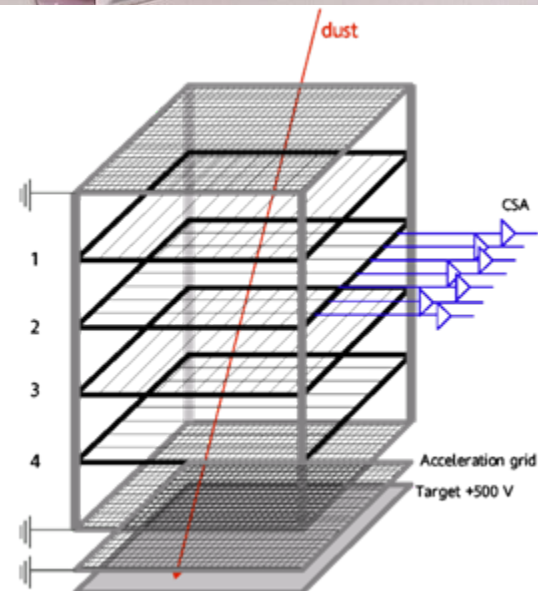
#### Measurements

- Dust motion, charge, size distribution, trajectory
- Electric fields
- Plasma temperature, density
- Plasma EM properties
- Medium - Long wavelength radio background



#### Potential Instruments for Consideration

- Dust Charge and Trajectory sensor
- Langmuir Probes (extensive heritage)
- Broadband Radio Receiver (various heritage)





## 4. Lunar Volatile Resource Analysis Package

### Measurements

Identify Solar Wind Implanted and other volatiles in the lunar regolith

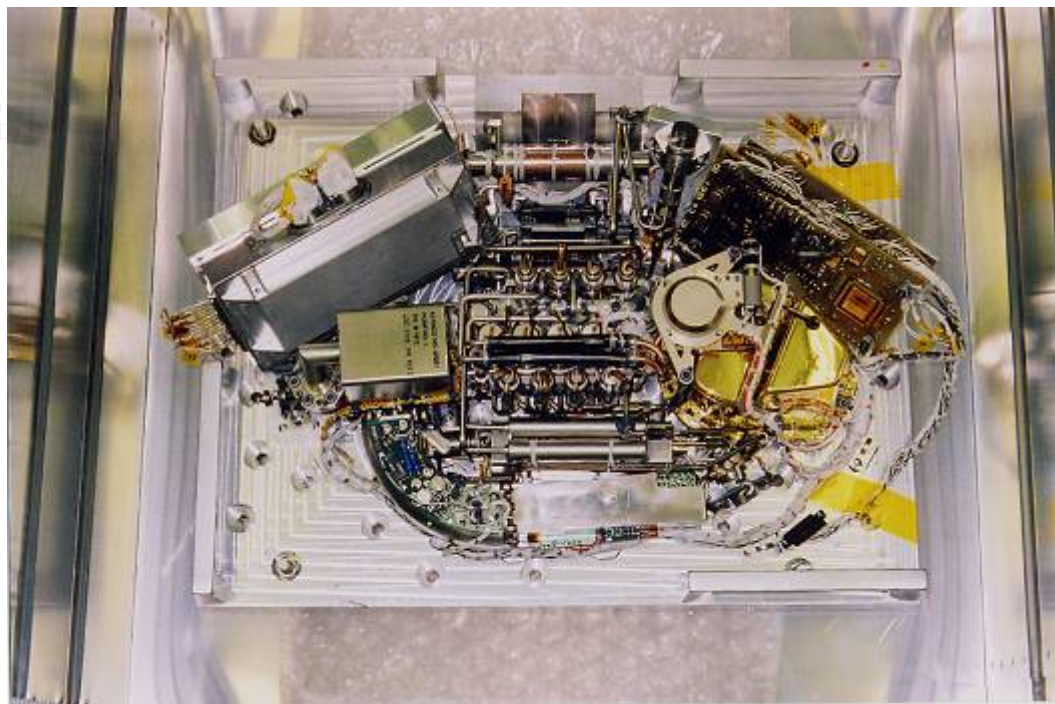
Extract volatiles from the lunar regolith as a potential resource

Observe exosphere species

Need to understand implications of surface contamination during landing

### Potential Instruments for Consideration

- Mass spectrometer (heritage e.g. Beagle 2 GAP)



*Beagle 2 GAP*



# Next Steps

- **Increase support basis to the Lunar Lander Mission with contributions from ESA Member States other than D, P, Canada. Other 3 countries expected to join before end 2010.**
- **Payload definition studies (GSP) – ITTs to be issued in October 2010**
- **Preparation for Ministerial Conference 2012**
- **Preparation for Call for Proposals / Announcement of Opportunity for the Lunar Lander Payload Instruments**



# Conclusions

- Europe's First Lunar Lander is a key step in preparing sustainable human exploration of the Moon and beyond
- The Lunar Lander will bring together the results of Europe's technological investment and experience, particularly in landing, to achieve a first in lunar exploration: landing at the Moon's south pole
- The Lunar Lander payload represents an important opportunity for the European research community

[www.esa.int/esaHS/exploration](http://www.esa.int/esaHS/exploration)